





WHAT IS AIRSKIN®?

AIRSKIN® is a soft and pressure sensitive safety skin for industrial robotics. It directly covers the entire robot as well as the tool and safely stops the machine in case of a collision. AIRSKIN® allows you to rethink robot safety in new and unconventional ways beyond limiting power and reach or restricting access.

WHY AIRSKIN®?



REMOVE THE FENCE
AND SAVE FLOOR SPACE



INCREASE SPEED FOR
SHORTER CYCLE TIMES



FAST AND EASY
RISK ANALYSIS



HIGHEST SAFETY
LEVEL PLe

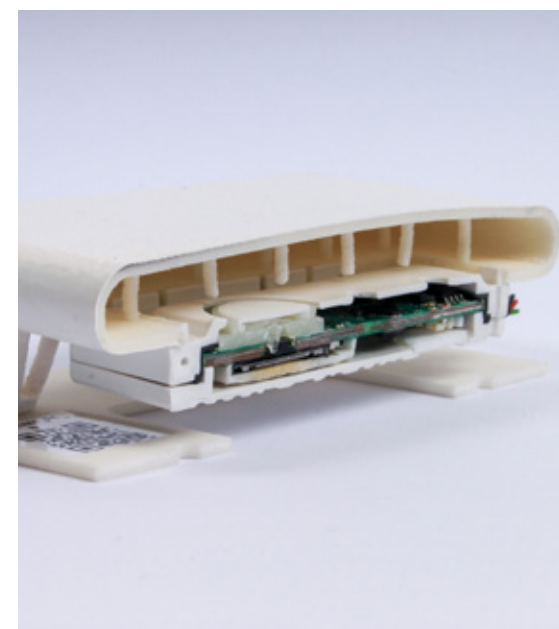


FAST INSTALLATION AND
MAINTENANCE



AVAILABLE AND CUSTOMIZABLE
FOR VARIOUS TOOLS/GRIPPERS

HOW IT WORKS



Soft, airtight sensor pads continuously monitor and reliably detect internal pressure changes due to deformations of the hull. Any collision immediately triggers a safe stop signal to the controller and initiates the robot's braking sequence. Remaining mechanical forces due to the stopping distance of the robot are absorbed by the soft padding.

The autonomous pads are connected to the controller's safety I/Os by a 6-wire cable carrying two redundant safety channels. Functional safety is ensured by constant self-diagnosis of the sensor pads. **AIRSKIN® fully complies with ISO 13849. It is certified as a PLe Cat.3 safety device by TÜV Austria.**



Electric Connection
24V power supply
2 redundant safety channel



Magnetic Connector
inherently safe electrical wiring



Soft & Durable Material
engineered for industrial
environment



3D Printed
custom pads for any tool

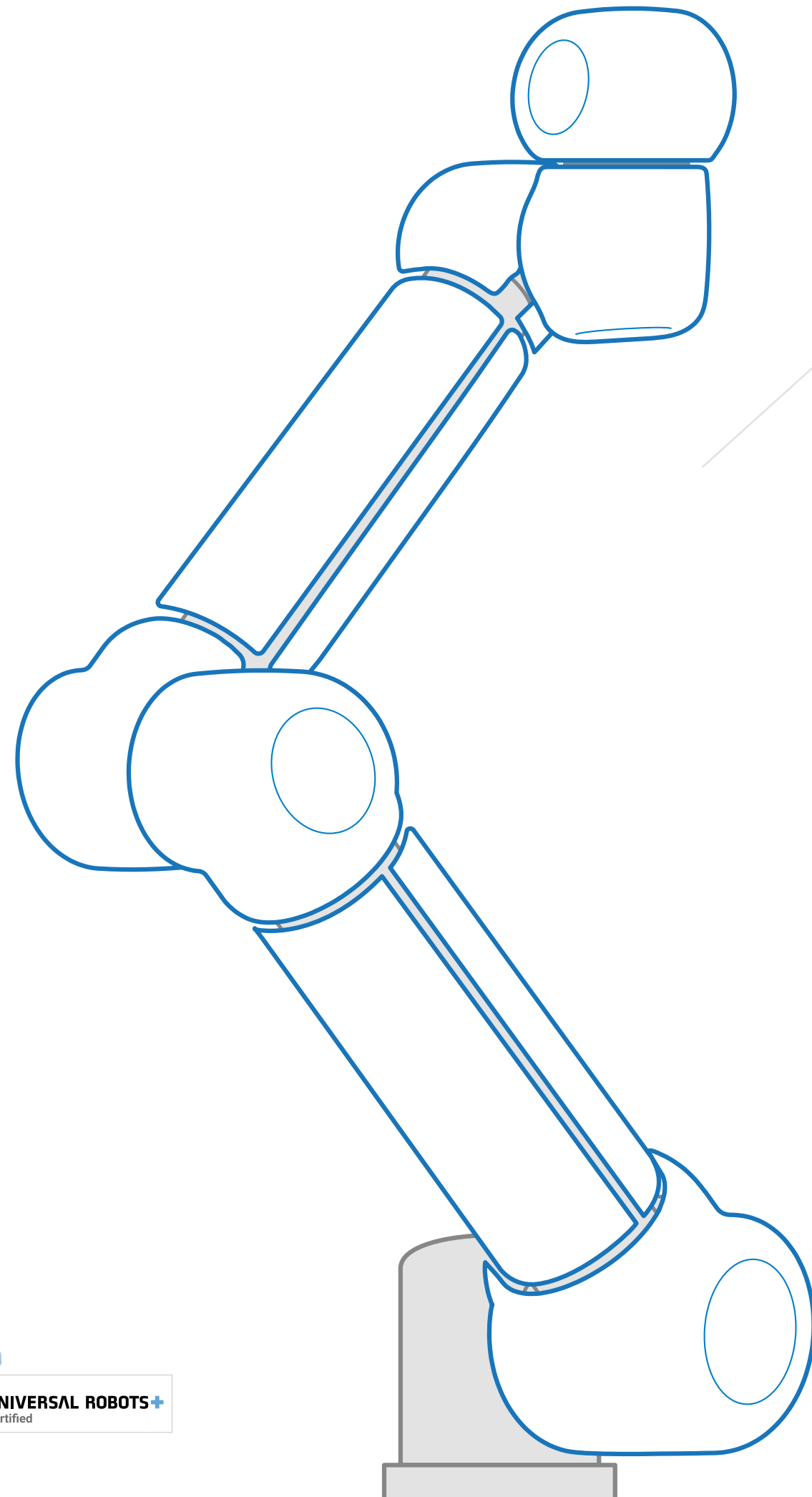


Heat dissipation
free airflow under pads



Visual feedback
intuitive status information

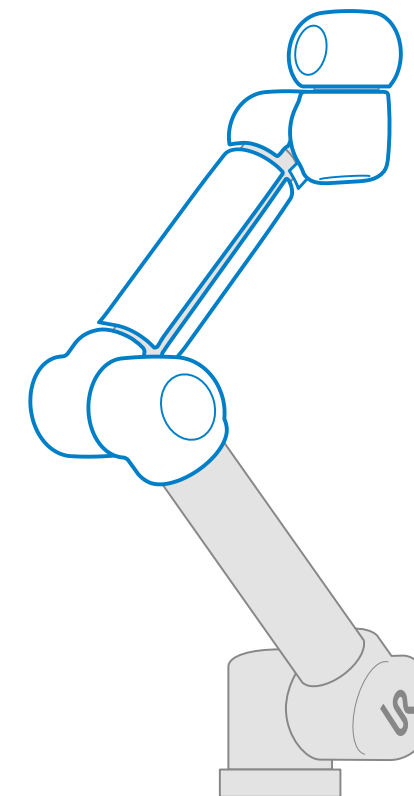
AIRSKIN



UR10 S2W

Shoulder2Wrist Kit

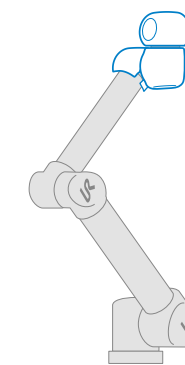
AIRSKIN® covering all moving axes.
Best option to cover a wide variety of applications.



UR10 E2W

Elbow2Wrist Kit

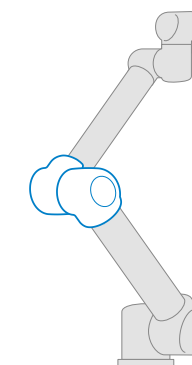
Good choice when the robot reaches into workspace or mounted overhead.



UR10 3W

Wrist Safety Kit

When additional safety for the wrist and tool area is needed.



UR10 2E

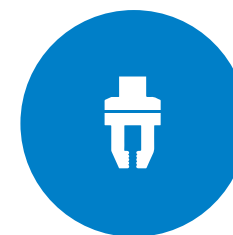
Elbow Safety Kit

For applications where only the elbow needs extra protection.



AIRSKIN® SAFETYFLANGE

This new safe flange adapter detects collisions in any direction of movement. It allows for real „finger safe“ collaborative pick-and-place applications with almost any tool and end effector. AIRSKIN® Safetyflange is mounted between the robot and the EoAT and provides compliance for the tool and the workpiece. The flange is based on AIRSKIN® technology and comes with PLe/Cat3 ISO 13849 safety certification.



APPLICABLE TO VARIOUS
TOOLS AND WORKPIECES

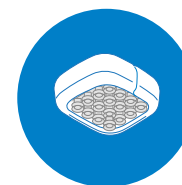


COMPLIANCE IN 4
DEGREES OF FREEDOM

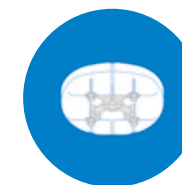


PALLETIZING

The new benchmark in safe palletizing applications: AIRSKIN® allows for faster movement speeds while completely eliminating clamping and shearing risks. ISO/TS 15066 compliance without a fence has never been easier!



ONROBOT VG10



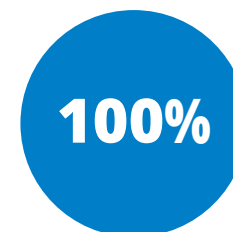
SCHMALZ COBOT PUMP



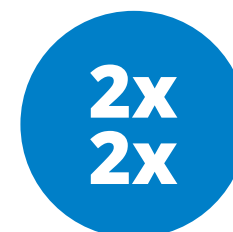
CUSTOMIZE YOUR OWN



WITHOUT A FENCE

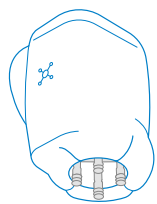


REDUCTION OF CLAMPING
AND SHEARING RISKS

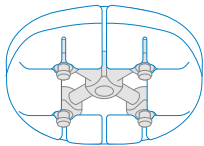


DOUBLE THE SPEED
DOUBLE THE PAYLOAD

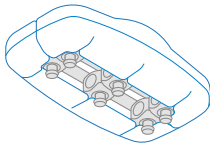
TOOLS



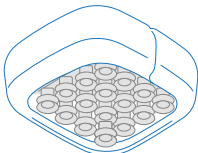
ETA-OPT SH-ZPN



SCHMALZ COBOT PUMP 2x2



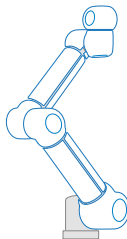
SCHMALZ COBOT PUMP 2x3



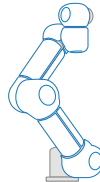
ONROBOT VG10



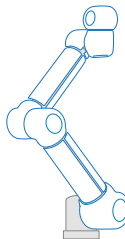
STÖGER CSX12



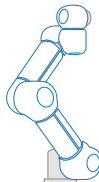
UNIVERSAL ROBOTS UR10



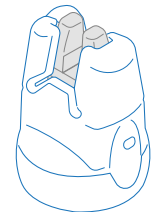
UNIVERSAL ROBOTS UR5



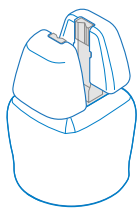
UNIVERSAL ROBOTS UR10e



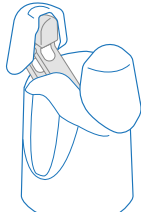
UNIVERSAL ROBOTS UR5e



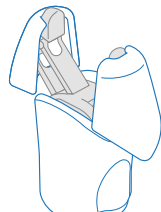
SCHUNK EGP-C



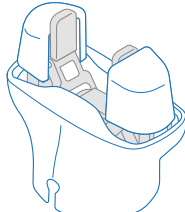
WEISS GRIPKIT-E2



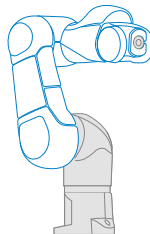
ONROBOT RG2



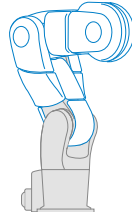
ONROBOT RG6



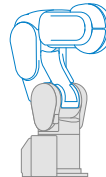
ROBOTIQ 2F-85



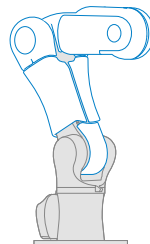
STÄUBLI TX2-90L



DENSO VS-087



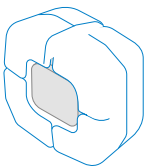
MITSUBISHI RV 4FL



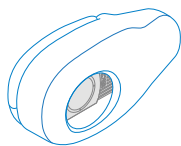
KUKA KR10



CAMERAS



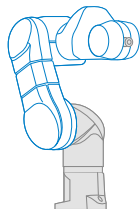
COGNEX IS76



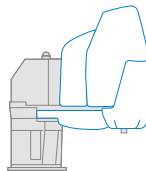
SICK PIM60



CUSTOMIZE YOUR OWN

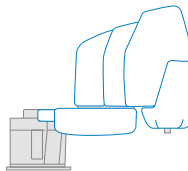


STÄUBLI TX2-60L



coming soon

EPSON T3 / LS3

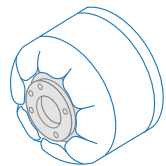


coming soon

EPSON T6 / LS6



FLANGES

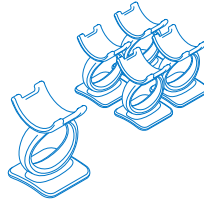


AIRSKIN® SAFETYFLANGE

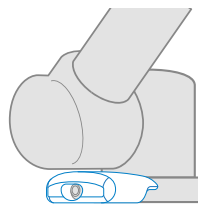
ADD ON



UR ENABLE SWITCH



UR CABLE CLAMP



CONNECTOR COVER



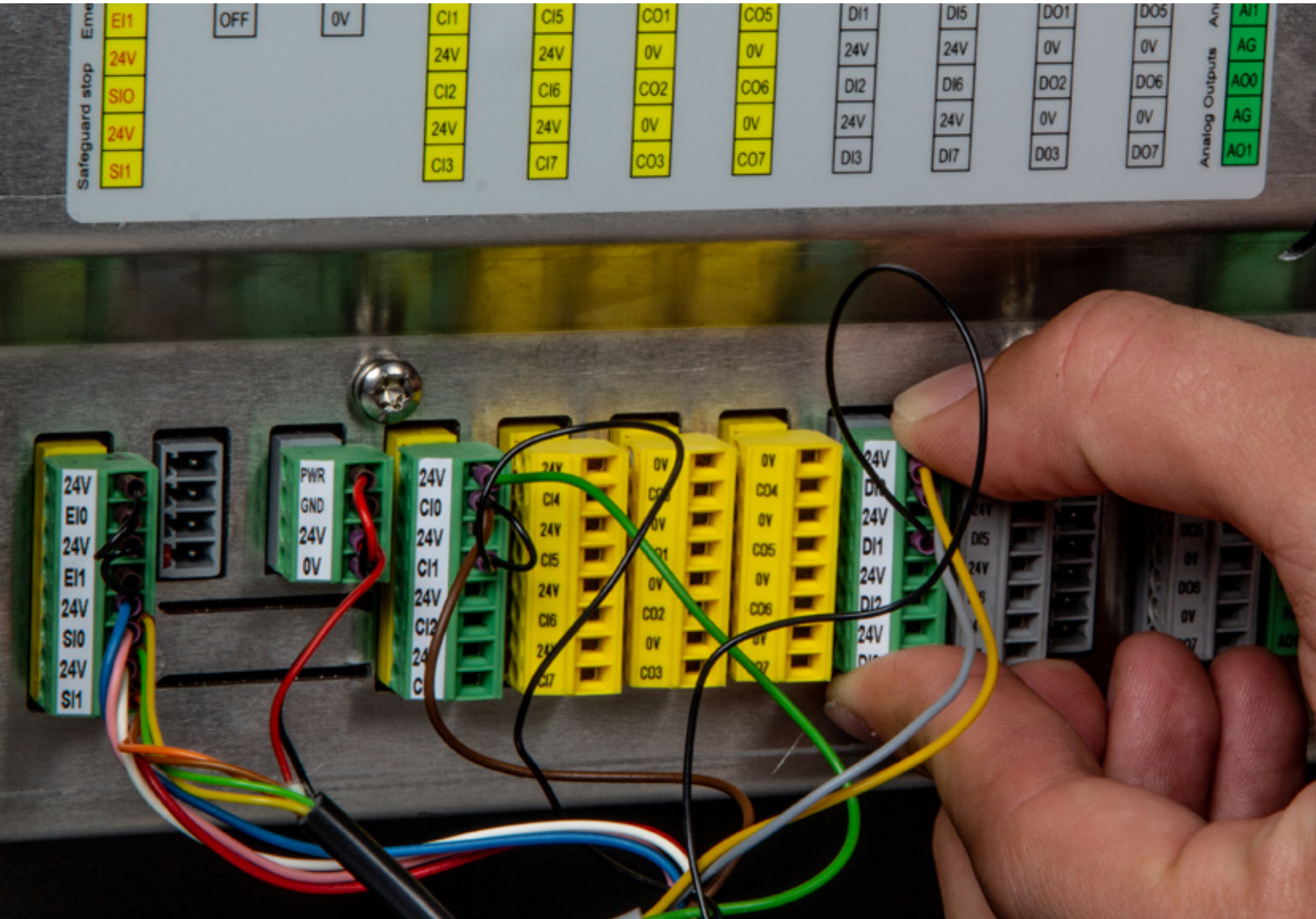
SPECIFICATIONS

TECHNICAL SPECIFICATIONS

- Reaction time**
< 9 ms
- Weight of a complete AIRSKIN® Set**
For a full UR10 robot with 10 pads: 3.7 kg
- Thickness on a robot**
Variable thickness of 20 - 80 mm possible
- Thickness on UR10**
20 mm, on average
- Mounting method / serviceability**
Support structure with snap-on AIRSKIN® pads
- Installation time**
30 min

ELECTRICAL SPECIFICATIONS

- Voltage supply**
24 V DC (ground bonding required)
- Electrical connection**
Directly from robot controller on UR10
- Operating current per AIRSKIN® pad**
10 mA, max. 35 mA
- Interface**
OSSD (6 Wires: 2 Safety Channels IN/OUT, 24V, Ground)
- Connection of AIRSKIN® to controller/PLC**
AIRSKIN® Connection Module with push-in contacts
- AIRSKIN® topology**
Daisy chain, max. 15 AIRSKIN® pads in a row
- Wiring**
Included in support layer with magnetic connectors



FEATURES

- IP classification**
IP50
- Chemical resistance**
Common cleaning solutions, oil, alcohol, sanitizer
- UV resistance**
100 %
- Tensile strength**
15 MPa, DIN 53504
- Skin shore hardness A**
~88, ISO 868
- Colours**
Standard white / grey. RAL on request
- Ambient temperature range**
5-40 °C
- Humidity level**
0 - 85 %
- Visual feedback**
RGB status LED per AIRSKIN® pad

STANDARDS AND NORMS

- Product classification**
ISO 13849 PLe / Cat 3
EN 62061 SIL3
- PFHd [1/h] with up to 15 AIRSKIN® pads**
<= 2.7e-8
- EC type examination No**
TÜV-A-MHF/MG/17-00411
- UL VDE (TPU skin)**
UL 94 V-2
- Flammability (TPU skin)**
UL 94 V-2



