The Future In Motion





The future of logistics automation is here

Mobile Industrial Robots (MiR) is a leading manufacturer of collaborative mobile robots. We are dedicated to develop user-friendly, flexible and safe robots to help companies increase their efficiency.

Our autonomous robots are a new generation of advanced mobile robots, which give you a rapid return on investment, often with a payback period of less than a year.

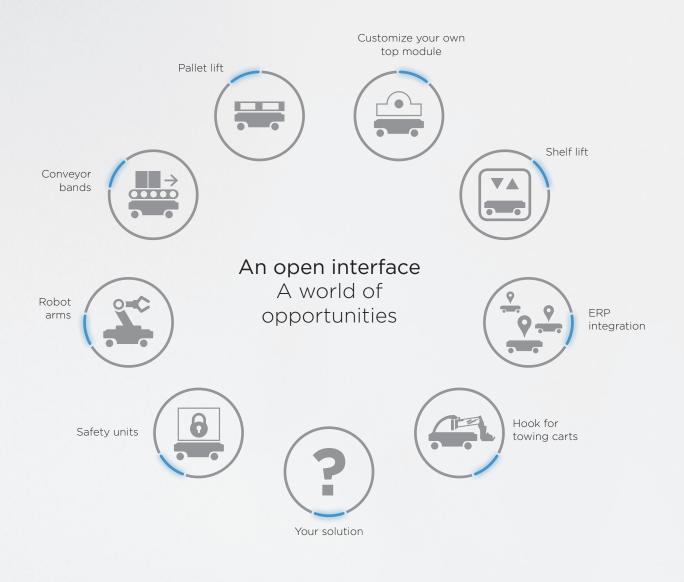
These unique, collaborative robots are now used by manufacturers in a wide range of industries and sectors, to automate their in-house transportation.

As a first mover in the field, we have enjoyed a rapid, worldwide adoption of our unique and innovative robots.

Reap all the benefits

- Install quickly and easily without changing the workplace layout.
- Can be redeployed for different tasks with various topmodules.
- Very user-friendly and is easily programmed with no prior experience needed.
- Allows employees to focus on high-value activities, not deliveries.
- Automate material handling and internal logistics.
- Enhance production flow and make significant progress.
- Safely and efficiently maneuvers around people and obstacles.
- Eliminates material flow bottlenecks to increase productivity.
- Offers fast ROI.





MiR Trade Forum

MiR TradeForum is our online showroom where you can see different accessories made by our distributors and by integrators for the customization of our mobile robots.

Be inspired and see how you can use the robots from MiR in different applications. Check it out; maybe there is just the accessory you need in order to optimize your internal logistics.

Visit http://www.mir-robots.com/mir-tradeforum/







MiR100



Safe and cost-effective mobile robots

The MiR100 and MiR200 are safe, cost-effective mobile robots that quickly automates your internal transportation and logistics. The robots optimize workflows, freeing staff resources so you can increase productivity and reduce costs. The highly flexible mobile robots autonomously transport up to 200 kg (440 lbs). They can be mounted with customized top modules such as bins, racks, lifts, conveyors or even a collaborative robot arm—whatever your application demands. Top modules are easy to change so the robot can be redeployed for different tasks.

MiRFleet

Fleet management for optimized robot traffic

- Fast and central configuration of a fleet of robots. Automatic prioritization and selection of the robot which is best suited for a job, based on position and availability.
- Planning of the use of different top modules, hook, and other accessories.
- Full featured REST-API for ERP implementation.









MiRHook

Automated in-house transport solutions

Autonomously picks up and unloads carts and is ideal for a wide range of towing jobs.

Moves heavy products between locations effectively.

> Highest position above ground: 1180 mm 46.5 in

Lowest position above ground: 1275 mm 50.2 in

TOWING CAPACITY: 500 kg / 1100 lbs

MiR

TOWING CAPACITY: 300 kg / 661 lbs

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Nidec

Three MiR100 with MiRHooks optimize the internal transportation of carts at German Nidec. Each robot drives 11 km a day, and they autonomously pickup, transport and deliver carts in two different production areas and move them to the warehouse.

Taking over the repetitive transportation tasks, the mobile robots free up employees for R&D while they are also keeping the stock low as they are able to move materials from the assembly lines immediately.

THE REAL

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MiR500 transports heavy loads and pallets autonomously. With the MiR500 Lift or EU Pallet Lift, the robot can automatically pick up, transport and deliver pallets.



MiR500 is designed to automate the transportation of pallets and heavy loads across industries. With a payload of 500 kg and a footprint of 1350x920 mm, MiR500 is the largest, most powerful robust collaborative, autonomous mobile robot from MiR.

With the MiR500 EU Pallet Lift or the MiR500 Lift, the MiR500 picks up, transports and delivers pallets autonomously, freeing up employees for more valuable tasks. MiR500 is compliant with ISO/EN 13849 and fulfills the EMC requirement for industrial and light industrial use. The rugged MiR500 is designed for industry use with robust exterior that can withstand dropped cargo and can easily navigate up and down ramps and even through shallow water puddles.



MiR500 Lift

MiR500 EU Pallet Lift



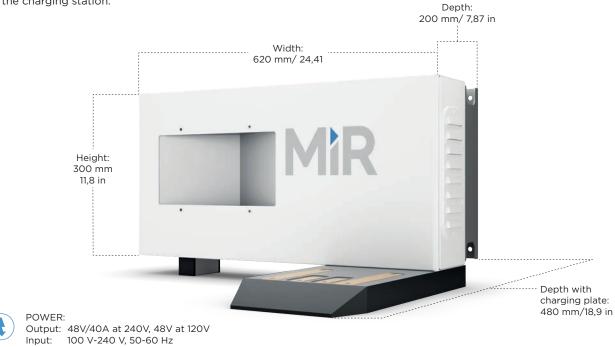




MiRCharge500

A fully automatic charging solution

The MiR500 move and connect autonomously to the charging station.



Johnson Controls Hitachi

A MiR200 improves the productivity and safety at Johnson Controls Hitachi in Barcelona. The mobile robot picks up shelving units in the storeroom and carries materials to the production line where it picks up waste packaging.

The robot operates during a full 8-hour shift and has eliminated electric trolleys from the factory floor, making it a safer place for all.

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Hours pr. day 64-072

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DESIGNATED USE	MìR 100	MìR 200	MiR 500
Collaborative mobile robot	For smaller transport tasks within the industry, logistics and healthcare	For smaller transport tasks within the industry, logistics and healthcare	for internal transportation of heavy loads and pallets within the industry and logistics
DIMENSIONS			
Length	890 mm / 35 in	890 mm / 35 in	1350 mm / 53 in
Width	580 mm / 22.8 in	580 mm / 22.8 in	920 mm / 36.2 in
Height	352 mm / 13.9 in	352 mm / 13.9 in	320 mm / 12.6 in
Height above floor	50 mm / 2 in	50 mm / 2 in	30 mm / 1.2 in
Weight (without load)	65 kg / 143 lbs	65 kg / 143 lbs	250 kg / 551 lbs
Load surface	600 x 800 mm	600 x 800 mm	1300 x 900 mm
COLOR			
RAL color	RAL 9010 / Pure White	RAL 7011 / Iron Grey	RAL 7011 / Iron Grey
PAYLOAD			
Robot Payload	100 kg / 220 lbs (maximum 5% incline)	200 kg / 440 lbs (maximum 5% incline)	500 kg / 1100 lbs
Towing Capacity	300 kg / 660 lbs (see MiRHook 100 specifications)	500 kg / 1100 lbs (see MiRHook 200 specifications)	
SPEED AND PERFORMANCE			
Battery running time	10 hours or 20 km / 12 mi	10 hours or 15 km / 9 mi	8 hours
Maximum speed	Forwards: 1.5 m/s (5.4 km/h) Backwards: 0.3 m/s (1 km/h)	Forwards: 1.1 m/s (4 km/h) Backwards: 0.3 m/s (1 km/h)	1.2 m/s - upgrade kit for 2.0 m/s speed available from 01.01.2019
Turning Radius	520 mm / 20 in (around center of robot)	520 mm / 20 in (around center of robot)	
Positioning accuracy	+/- 50 mm / 2 in of position, +/- 10 mm / 0.4 to docking marker	+/- 50 mm / 2 in of position, +/- 10 mm / 0.4 to docking marker	
Traversable gap and sill tolerance	20 mm / 0.8 in	20 mm / 0.8 in	
POWER			
Battery	Li-NMC, 24 V, 40 Ah	Li-NMC, 24 V, 40 Ah	Li-NMC, 48 V, 40 Ah
Charging time	With cable: up to 4.5 hours (0-80%: 3 hours) With charging station: up to 3 hours (0-80%: 2 hours)	With cable: up to 4.5 hours (0-80%: 3 hours) With charging station: up to 3 hours (0-80%: 2 hours)	1 hour (10% to 90%) MiR Charge 2 hours (10% to 90%) cable charger
External Charger	Input: 100-230 V ac, 50-60 Hz Output: 24 V, max 15 A	Input: 100-230 V ac, 50-60 Hz Output: 24 V, max 15 A	Input: 100-230 V ac, 50-60 Hz / Output: 48 V, max 40 A
Battery charging cycle			Minimum 600 cycles
ENVIRONMENT			
Ambient temperature range	+5°C to 50°C (humidity 10-95% non-condensing)	+5°C to 50°C (humidity 10-95% non-condensing)	+5°C to 40°C (humidity 10-95% non-condensing)
IP Class	IP 20	IP20	IP21
Certifications	CE certified Clean Room Certified	ESD certified Clean Room Certified ESD Approved	5 safety functions according to ISO 13849-1 EMC: EN61000-6-2, EN61000-6-3
COMMUNICATION			
WiFi	Dual-band wireless AC/G/N/B	Dual-band wireless AC/G/N/B	Dual-band wireless AC/G/N/B
Bluetooth	4.0 LE, range: 10-20 m / 33-66 ft	4.0 LE, range: 10-20 m / 33-66 ft	
I/Os	USB and Ethernet	USB and Ethernet	4 digital inputs, 4 digital outputs, 1 Ethernet port with Modbus protocol
SENSORS			
SICK microScan3 safety system (2 pcs.)	SICK safety laser scanners S300 (front and back) 360° visual protection around robot	SICK safety laser scanners S300 (front and back) 360° visual protection around robot	360° visual protection around robot
3D camera (2 pcs.)	3D camera Intel RealSense™ Detection of objects ahead 50-500 mm above floor	3D camera Intel RealSense™ Detection of objects ahead 50-500 mm above floor	2 psc.: Intel RealSense D435. FoV: Detects objects 1700 mm high at a distance of 950 mm in front of the robot. 114° total horizontal view. Ground view, minimum distance from robot: 250 mm
TOP MODULE			
Max. height from floor to top	1800 mm / 70 in	1800 mm / 70 in	
Center of gravity	< 900 mm / 35 in above the floor	< 900 mm / 35 in above the floor	

	MiRHook100	MiRHook200
DESIGNATED USE		
Collaborative mobile robot with hook	for fully-automated pick-up and delivery of carts	for fully-automated pick-up and delivery of cart
DIMENSIONS		
Length (highest to lowest positions of hook arm)	1180 to 1275 mm / 46.5 to 50.2 in	1180 to 1275 mm / 46.5 to 50.2 in
Width	580 mm / 22.8 in	580 mm / 22.8 in
Height (lowest to highest positions of hook arm)	550 to 900 mm / 21.7 to 35.4 in	550 to 900 mm / 21.7 to 35.4 in
Height above floor	Robot: 50 mm / 2 in Gripping height: 50-390 mm / 2-13.4 in	Robot: 50 mm / 2 in Gripping height: 50-390 mm / 2-13.4 in
Weight (without load)	98 kg / 216 lbs	98 kg / 216 lbs
COLOR		
RAL color	RAL 9010 / Pure White	RAL 7011 / Iron Grey
TOWING CAPACITY		
Load incl. cart	Up to 300 kg / 661 lbs at <1 % incline 200 kg / 441 lbs at 5% incline	Up to 500 kg / 1100 lbs at <1 % incline 300 kg / 661 lbs at 5% incline
SPEED AND PERFORMANCE		
Running time (depending on load)	8-10 hours or 15-20 km / 9.3-12.4 mi	8-10 hours or 15-20 km / 9.3-12.4 mi
Maximum speed	1.5 m/s (5.4 km/h) / 4.9 ft/s (3.6 mph)	1.1 m/s (4 km/h) / 3.6 ft/s (2.5 mph)
Turning radius (without cart)	520 mm / 20.5 in (around center of robot)	520 mm / 20.5 in (around center of robot)
Swinging radius (with cart)	Total length of robot and cart plus 550 mm / 21.7 in	Total length of robot and cart plus 550 mm / 21.7 in
Positioning accuracy (placing cart)	+/- 200 mm / 7.9 in from center of position, 10° accuracy	+/- 200 mm / 7.9 in from center of position, 10° accuracy
POWER		
Battery	Li-NMC, 24 V, 40 Ah	Li-NMC, 24 V, 40 Ah
Charging time	Up to 3 hours (0-80%: 2 hours)	Up to 3 hours (0-80%: 2 hours)
Internal charger	Input: 100-230 V ac, 50-60 Hz Output: 24 V, max 15 A	Input: 100-230 V ac, 50-60 Hz Output: 24 V, max 15 A
ENVIRONMENT		
Ambient temperature range (humidity 10-95% non-condensing)	+5°C to 50°C	+5°C to 50°C
IP class	IP20	IP20
COMMUNICATION		
WiFi	Dual-band wireless AC/G/N/B	Dual-band wireless AC/G/N/B
Bluetooth	4.0 LE, range: 10-20 m / 32.8-65.6 ft	4.0 LE, range: 10-20 m / 32.8-65.6 ft
I/Os	USB and Ethernet	USB and Ethernet
SENSORS		
SICK safety laser scanners S300 (front and back)	360° visual protection around robot	360° visual protection around robot
	detection of objects ahead 50-500 mm / 2-20 in above floor	detection of objects ahead 50-500 mm / 2-20 in above floor
on robot 3D camera Intel RealSense™		
on robot 3D camera Intel RealSense™ on front of hook	50-500 mm / 2-20 in above floor detection of objects ahead up to	50-500 mm / 2-20 in above floor detection of objects ahead up to
on robot 3D camera Intel RealSense™ on front of hook CART	50-500 mm / 2-20 in above floor detection of objects ahead up to	50-500 mm / 2-20 in above floor detection of objects ahead up to
3D camera Intel RealSense™ on robot 3D camera Intel RealSense™ on front of hook CART Length Width	50-500 mm / 2-20 in above floor detection of objects ahead up to 2000 mm / 78.7 in above floor	50-500 mm / 2-20 in above floor detection of objects ahead up to 2000 mm / 78.7 in above floor

MiR500 Lift

DESIGNATED USE

for autonomous pickup and unloading of pallets and for lift applications

MiR500 EU Pallet Lift

for autonomous pickup and unloading of EUR-pallets

Lift for MiR500

DIMENSIONS		
Length	Frame Length: 1304 mm / 51.3 in Lift Length: 1174 mm / 46.2 in	1200 mm / 47.2 in
Width	Frame Width: 910 mm / 35.8 in Lift Width: 710 mm / 28 in	162 mm / 6.4 in
Total height in lowered position	90 mm / 3.5 in	95 mm / 3.7 in
Total height in lifted position	150 mm / 5.9 in	155 mm / 6.1 in
COLOR		
RAL color	Frame color: RAL 7011 / Iron Grey Lift Color: RAL 9005 / Signal Black	RAL 9005 / Signal Black
PAYLOAD		
Lift Payload	500 kg / 1100 lbs	500 kg / 1100 lbs
PERFORMANCE		
Lift height	60 mm / 2.4 in	60 mm / 2.4 in
Lifting cycle	Minimum 50,000 cycles	Minimum 60,000 cycles

PALLETS

Length x width

Supported with MiR500 Lift Pallet Rack: 1016 mm x 1219 mm / 40 in x 48 in Can be used for different pallet dimensions

1200 mm x 800 mm / 47.2 x 31.5 in



	MiR500 Lift Pallet Rack	MiR500 EU Pallet Rack
DESIGNATED USE		
Pallet Rack for MiR500	for autonomous pickup and unloading of 40" x 48" pallets	for autonomous pickup and unloading of EUR-pallets
DIMENSIONS		
Length	1300 mm / 51.2 in	1300 mm / 56.3 in
Width	1182 mm / 45.5 in	1182 mm / 45.5 in
Height	442 mm / 17.4 in	352 mm / 13.9 in
COLOR		
RAL color	RAL 7011 / Iron Grey	RAL 7011 / Iron Grey
PAYLOAD		
Pallet Rack payload	500 kg / 1100 lbs	500 kg / 1100 lbs

DESIGNATED USE





MiRCharge

MiRCharge500

Automatic charger for MiR robots	The robot moves and connects to the docking station.	The robot moves and connects to the docking station
DIMENSIONS		
Width	580 mm / 22.8 in	620 mm
Height	300 mm / 11.8 in	340 mm
Depth	120 mm / 4.7 in	200 mm (with charging plate: 480 mm)
Weight	10.5 kg / 22 lbs	21 kg
MOUNTING SPECIFICATIONS		
Wall mounting	to be mounted flush with floor	
Mounting height above	floor 45 mm / 1.8 in from floor to bottom edge	
RATED OPERATING CONDITIO	NS	
Ambient temperature range	+5°C to 50°C	+5°C to 40°C
Humidity	10-95% non-condensing	10-95% non-condensing
Power	Output. 24 V, max. 25 A Input: 100/230 V ac, 50-60 Hz	Output. 48V/40A at 240V, 48V at 120V Input: 100 V-240 V, 50-60 Hz
COMPLIANCE		
Standard	EN 60204-1	EN 60204-1

	MiRFleet
DESIGNATED USE	MIRTICEL
Centralized control of a fleet of robots	Up to 100 robots
Order handling	Prioritization and handling of orders among multiple robots
Battery level control	Monitoring of robot battery levels and automatic handling of recharging
Traffic control	Coordination of critical zones with multiple robot intersections
TWO VERSIONS AVAILABLE	
Linux PC	Comes as a physical PC box
Virtual Machine Image	For installation in existing server system
MIRFLEET PHYSICAL LINUX PC	
PC type	Intel® Maple Canyon NUC
CPU	Intel® Core i3-5010U (3MB cache, 2.1GHz base clock)
RAM	8GB DDR3L-1600
SSD	120GB 2.5"
Operating system	Linux Ubuntu 16.04
Network capabilities	1 Gbit Ethernet, no wireless option
Required connections	110 V or 230 V power socket and Ethernet network cable
Installation requirements	Must run on the same physical network as the robots
MIRFLEET VIRTUAL MACHINE IMA	GE
Image file size	3 GB
Server requirements	Dual core processor with min, 2.1 GHz clock
RAM	Min. 4 GB (8 GB recommended)
HDD	10 GB
Virtualization software	Oracle VirtualBox or VMware



Zealand University Hospital

Five hospital departments at Zealand University Hospital in Denmark receive daily autonomous deliveries from the hospital's sterilization center with a MiR100. Before the mobile robot arrived, service assistants were providing weekly deliveries of disposable equipment to hospital departments. A manual procedure that involved heavy lifting.

Now the MiR100 improves the ergonomics, make sure that deliveries are made on time, and frees up time for the service assistants to do warmer tasks like patient care.





Born Global

Mobile Industrial Robots is rapidly expanding. We have established offices in Denmark (HQ), New York, Spain, Germany, China, San Diego, and Singapore and with **+150 distributors** in more than **40 countries** and still more to come, we are able to offer our robots to customers worldwide.



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